Section 3.5

Math 231

Hope College



Subspaces Associated to a Matrix

Let $A \in M_{m,n}(\mathbb{R})$.

• The null space of A is defined as

$$NS(\boldsymbol{A}) = \{ \vec{\mathbf{x}} \in \mathbb{R}^n \, | \, \boldsymbol{A}\vec{\mathbf{x}} = \vec{\mathbf{0}} \}.$$

- The column space of A is the span of the columns of A, considered as vectors in ℝ^m. The column space of A is denoted by CS(A).
- The row space of A is the span of the rows of A, considered as vectors in ℝⁿ. The row space of A is denoted by RS(A).

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Let $A \in M_{m,n}(\mathbb{R})$.

• (Theorem 3.48) To find a basis for NS(*A*), first solve $A\vec{\mathbf{x}} = \vec{0}$ and parameterize the solution set with parameters t_1, t_2, \dots, t_k . Write this solution as

$$\vec{\mathbf{x}} = \vec{\mathbf{x}}_1 t_1 + \vec{\mathbf{x}}_2 t_2 + \cdots + \vec{\mathbf{x}}_k t_k.$$

- The columns of *A* corresponding to leading columns in rref (*A*) can be combined to form a basis of CS(*A*). (See Theorem 3.47.)
- (Theorem 3.49) The nonzero rows of rref (*A*) form a basis for RS(*A*).
- It is important here to use the columns of the original matrix A for the basis of CS(A) and the rows of rref (A) for the basis of RS(A).

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